

Gen IV Controller Modbus TCP Instructions

The AcraDyne controller supports the Modbus/ TCP Server protocol on the local Ethernet port. The controller can accept messages from a Modbus/TCP Client and return responses to the Client.

From the main menu, select Controller.

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Select IO.

Controller Configuration Menu	
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Following are the Modbus TCP options



Supported Features:

The Modbus/TCP server supports the Modbus RTU protocol. Modbus RTU is a communication protocol that represents devices as "Registers" and "Coils." Modbus TCP defines multiple classes of devices based on functionality. The controller is a Class 1 device supporting all Class 0 and 1 functions.

- Class 0 devices must support function codes 3 and 16.
- Class 1 devices must support function codes 1–7 and 16.

The supported functions are:

- Function Code 1 Read Coil Status
- Function Code 2 Read Input Status
- Function Code 3 Read Holding Registers
- Function Code 4 Read Input Registers
- Function Code 5 Force Single Coil
- Function Code 6 Write Single Holding Register
- Function Code 7 Read Exception Status
- Function Code 16 Write Multiple Holding Registers

Controller Outputs Addressing

The controller's assignable outputs are mapped as Modbus TCP input registers. The first two assignable output bytes are register 0 followed by register 1 (bytes 2 & 3). Since Modbus TCP uses 16 bit registers it is helpful to create assignments with a size of INT16. The controller's outputs can read with function code 4 "Read Input registers."



The controller's outputs can also be addressed as coils. The assigned outputs start at coil #16.

The controllers outputs can be read with function code 2 "Read Input Status."



Controller Inputs Addressing

The controller's assignable inputs are mapped as Modbus TCP holding registers. The first two assignable input bytes are register 1000 followed by register 1001 (bytes 2 & 3). Since Modbus TCP uses 16 bit registers it is helpful to create assignments with a size of INT16. The controller's inputs can be written with function code 6 "Write Single Holding register" and function Code 16 "Write Multiple Holding registers." The controller's inputs can also be read with function Code 3 "Read Holding registers."



The controller's inputs can also be addressed as coils. The assigned inputs start at coil #1015.

The controller's inputs can be written with function code 5 "Force Single Coil." The controller's inputs can also be read with function code 1 "Read Coil Status."



Modbus TCP Inputs

These types of communication are useful for data communication between controller and PLCs. It is an effective, quick way for the data transfer of short data packages.



Element Type: Choose from Byte, Int16, Int32, or ASCII.

Element: Shows element # being configured

Bit (not shown): Enter Bit #.

Bits: # of bits the assignment will read.

Start at: Starting bit location.

Polarity (not shown): Select Normally Open (N.O.) or Normally Closed Outputs (N.C.).

Length (not shown, available in ASCII ID function): Number of characters desired to send.

Torque (not shown, available in Click Wrench function): Torque value to be reported when using Click Wrench input. Value input is what will be sent from controller when Input Signal is received from a Click Wrench. Value is NOT calculated by the controller rather it is solely what the Click Wrench is calibrated to by outside means.

Torque Units (not shown, available with Click Wrench function): Choose from Nm, Kgm, Kgcm, Ftlb, and Inlb.

Function: See the Gen IV Controller User Manual for more details. Select desired Input Function(s).

Click on **v** after appropriate selections are made.





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